Fast, accurate and differentiable simulations of weak cosmic lensing

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MADLens



Weak Cosmic Shear

Weak gravitational lensing coherently distorts (shears) observed galaxy shapes.





DES Collaboration 2017 (arxiv: 1708.01530)



Lensing is sensitive to

- the total matter parameter ($oldsymbol{\Omega}_{m}$)
- the amplitude of matter fluctuations $(\boldsymbol{\sigma}_{s})$
- sum of neutrino masses (\mathbf{M}_{v})
- time-varying dark energy (w)







posterior analysis

- optimization (find maximum)
- sampling (get contours, mean)











e.g. CFHTLens Analysis, Lu et al. 2008

Scientist-defined non-Gaussian summary statistics



e.g. Li et al. 2018 (arxiv: 1810.01781), Coulton et al. (**VB**) 2018 (arxiv: 1810.02374), Liu et al. (**VB**) 2016 (arxiv: 1608.03169)



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e.g. Ribli et al. 2019 (arxiv:1902.03663), Fluri et al. 2019 (arxiv: 1906.03156), Jeffrey et al. 2020 (arxiv:2009.08459), Taylor et al. 2019 (arxiv:1904.05364)











Particle Mesh Simulation + Lensing Projection

⇒ Lensing Convergence





VB, Y. Feng, M. Lee, B. Dai 2021 (arxiv: 2102.13618)



Particle Mesh Simulation + Lensing Projection ⇒ Lensing Convergence







1 https://github.com/VMBoehm/MADLens

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Particle Gradient Descent

Particle Gradient Descent² (PGD) displaces particles in every step to recover particle positions of a high resolution simulation.

 $\mathbf{S}(x,a) = \alpha(a)/H_0^2 \left[\nabla \phi_{\text{filtered}}(x,a) \right]$





²Dai et al. 2016 (arxiv:1603.00476)

MADLens allows the user to take accurate derivatives through the simulation

- 1) with respect to the initial conditions
- 2) with respect to cosmological parameters



Memory efficient derivatives of scalar functions rely on reverse mode differentiation, a technique used in deep learning for training neural networks.

$$y = F(x) \qquad y \in R, x \in R^N \qquad F = A \circ B \circ C \qquad \begin{array}{l} y = A(a) \\ a = B(b) \\ b = C(x) \end{array}$$

Forward-mode differentiation:

$$\frac{\partial F}{\partial x}|_{x_0} = \frac{\partial A}{\partial a}|_{a_0} \left(\frac{\partial B}{\partial b}|_{b_0}\frac{\partial C}{\partial x}|_{x_0}\right) = J_A \cdot \left(J_B \cdot J_C\right)$$
large matrix

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Reverse-mode differentiation:

$$\frac{\partial F}{\partial x}|_{x_0} = \left(\frac{\partial A}{\partial a}|_{a_0}\frac{\partial B}{\partial b}|_{b_0}\right)\frac{\partial C}{\partial x}|_{x_0} = (J_A \cdot J_B) \cdot J_C$$

requires saving results of forward pass on a tape

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Based on backpropagation (a method also used for training neural networks).





MADLens for Data Analysis



work led by Max E.





Lee et al. (VB) in prep.

$$P(\eta|d) \sim \int \mathrm{d}s \, P(s,\eta|d)$$

VB et al. 2017 (arxiv:1701.01886)



MAP reconstruction with MADLens



MADLens for Data Analysis



work led by Max E.



VB et al. 2017 (arxiv:1701.01886)







MAP reconstruction with MADLens



MADLens is the most accurate fast lensing code to date - and it is open source!

https://github.com/VMBoehm/MADLens

We can help you get it running for your application and welcome feedback.

We are actively working on extending MADLens (adding observables that are correlated with the convergence field, adding more derivatives).

The MADLens lensing scheme is currently being integrated into FlowPM (Modi et al 2020) - a FastPM version in tensorflow that runs on GPUs.